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THE DEFLECTION COIL OF AN X-RAY TUBE"

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In accordance with the provisions of 37 C.F.R. §501, the patent owner herewith makes the following documents of record in the United States prosecution file for the above-referenced patent.

United States Patent No. 5,682,412

PCT Application WO 98/17055

These references were cited in an Office Action rendered by the German Patent and Trademark Office in connection with the counterpart German application after the allowance of the present application. These references are cumulative to the references made of record during

prosecution herein, and would not have required any alteration in the claim language.

A copy of PCT Application WO 98/17055 is submitted herewith.

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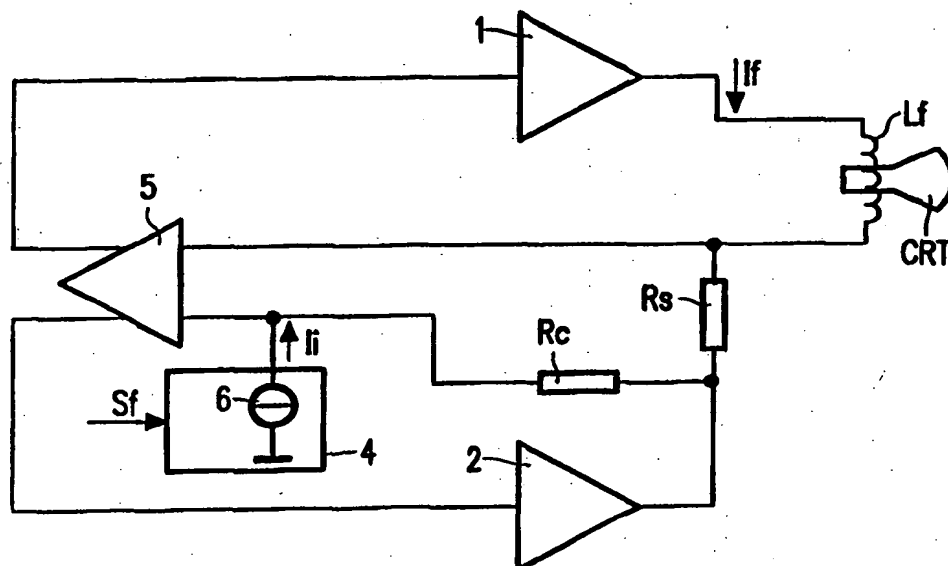
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(21) International Application Number: PCT/IB97/01110 (22) International Filing Date: 16 September 1997 (16.09.97) (30) Priority Data: 96202854.4 14 October 1996 (14.10.96) EP (34) Countries for which the regional or international application was filed: NL et al. (71) Applicant: PHILIPS ELECTRONICS N.V. [NL/NL]; Groenewoudseweg 1, NL-5621 BA Eindhoven (NL). (71) Applicant (for SE only): PHILIPS NORDEN AB [SE/SE]; Kottbygatan 7, Kista, S-164 85 Stockholm (SE). (72) Inventors: VAN TUIJL, Adrianus, Johannes, Maria; Prof. Holstlaan 6, NL-5656 AA Eindhoven (NL). VAN DER VEN, Erik; Prof. Holstlaan 6, NL-5656 AA Eindhoven (NL). (74) Agent: GROENENDAAL, Antonius, W., M.; Internationaal Octrooibureau B.V., P.O. Box 220, NL-5600 AE Eindhoven (NL).			(81) Designated States: JP, KR, European patent (AT, BE, CH, DE, DK, ES, FI, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE).  Published Without international search report and to be republished upon receipt of that report.

(54) Title: DEFLECTION WITH LOW OFFSET

## (57) Abstract

A series arrangement of a deflection coil ( $L_f$ ) and a series resistor ( $R_s$ ) is connected between an output of a first output amplifier (1) and an output of a second output amplifier (2) to be driven in a bridge configuration for generating a deflection current ( $I_f$ ) through the deflection coil ( $L_f$ ). Across the series resistor ( $R_s$ ), a voltage is generated which corresponds to the deflection current ( $I_f$ ). A differential amplifier (5) has a first input connected to a first end of the series resistor ( $R_s$ ). A second input of the differential amplifier (5) is connected to a second end of the series resistor ( $R_s$ ) via a conversion resistor ( $R_c$ ). An input current ( $I_i$ ) is generated through the conversion resistor ( $R_c$ ). The polarity of the input current ( $I_i$ ) is selected to obtain a voltage across the conversion resistor ( $R_c$ ) which has an opposite polarity with respect to the voltage across the series resistor ( $R_s$ ). The differential amplifier (5) has two outputs connected to respective inputs of the first and the second output amplifiers (1, 2) to drive the two output amplifiers (1, 2) in a feedback loop in such a manner that the voltage across the series arrangement of the conversion resistor ( $R_c$ ) and this series resistor ( $R_s$ ) is substantially zero. In this way, the voltage swing between the inputs of the differential amplifier (5) is very low and thus the offset voltage caused will be very low.



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Deflection with low offset.

The invention relates to a deflection circuit for generating an electron beam deflection current in a deflection coil, the deflection circuit comprising: a first and a second output amplifier, a series resistor arranged in series with the deflection coil, the series arrangement of the deflection coil and the series resistor being coupled between an output of  
5 the first output amplifier and an output of the second output amplifier, a differential amplifier having a first input coupled to a first end of the series resistor, and having outputs coupled to corresponding inputs of the first and the second output amplifier, respectively, for driving the first and second output amplifiers in a bridge configuration.

The invention also relates to a picture display apparatus comprising such a  
10 deflection circuit, and to an integrated circuit for use in such a deflection circuit.

The Philips Semiconductors Application Note AN95029 "TDA 8350 and TDA 8351 deflection output circuits Application information" discloses an integrated power circuit for use in a raster scan circuit. The integrated power circuit has a first and a second  
15 output amplifier which are arranged in a bridge configuration to generate a deflection current through a raster scan deflection coil. The deflection current generates a magnetic field deflecting electron beams in a cathode ray tube in the vertical direction. A measurement resistor is arranged in series with the deflection coil. Across this measurement resistor a voltage is generated which is related to the deflection current through the deflection coil. The  
20 voltage across the measurement resistor is sensed with a first voltage to current converter which has a first and a second current output. To provide a feedback, the first current output is connected to an input of the first output amplifier, and the second current output is connected to an input of the second output amplifier. The integrated power circuit further comprises a second voltage to current converter which has two inputs for receiving an input  
25 waveform occurring across an input resistor. The second voltage to current converter has a first and a second current output. The first current output is connected to the input of the first output amplifier, and the second current output is connected to the input of the second output amplifier. The first and the second voltage to current converters are identical. The current outputs of the first and the second voltage to current converters which are

interconnected supply output currents which have opposite polarities. In this way, the output voltages of the output amplifiers will be controlled such that the voltages across the measurement resistor and the input resistor are substantially equal. This implies that the ratio of the deflection current and the current through the input resistor is equal to the ratio of the input resistor and the measurement resistor.

In practical applications, the peak-peak voltage across the measurement resistor due to the deflection current is in the order of one volt. The same holds then for the peak-peak voltage of the input waveform. The first and second voltage to current converters comprise bipolar differential input stages to which emitter resistors are added to handle the high voltage swing. It is a drawback of the known deflection circuit that an offset voltage occurs due to mismatch of the emitter resistors. This offset voltage gives rise to a DC-shift of the deflected picture. An adjustment is needed to compensate for this DC-shift.

It is an object of the invention to provide a deflection circuit with an improved offset behaviour.

An aspect of the invention is characterized in that the deflection circuit further comprises a conversion resistor having: a first end coupled to a second input of the differential amplifier, the first end receiving an input current having an input waveform, and a second end coupled to a second end of the series resistor.

A further aspect of the invention provides a picture display apparatus comprising a deflection circuit as is defined in claim 10.

A further aspect of the invention provides a integrated circuit for use in a deflection circuit as is defined in claim 11.

Advantageous embodiments are defined in the subclaims.

In the deflection circuit according to the invention, the differential amplifier receives as an input voltage the voltage which occurs across the series arrangement of the conversion resistor and the series resistor. The input waveform is supplied as an input current through the conversion resistor. The polarity of the input current is selected to obtain an voltage across the conversion resistor which has an opposite polarity with respect to the voltage across the series resistor. The differential amplifier drives the two output amplifiers in a feedback loop such that the voltage across the series arrangement of the conversion resistor and the series resistor becomes equal to zero. In this way, the voltage swing between the inputs of the differential amplifier is very low and thus the offset caused is also very low. In generally known AC-coupled frame deflection circuits, a low offset is not an issue as it

does not cause a DC-shift. It is a further advantage of the low offset that in the selection of the scan supply voltage it is not needed to take account of a possibility to adjust for a DC-offset, which enables an as low scan supply voltage as possible thereby reaching a higher efficiency. Also, the influence of aging and temperature on the offset will be negligible.

5 In an embodiment of the invention as claimed in claim 2, the influence on the feedback of the current flowing through a damping impedance arranged in parallel with the deflection coil is compensated at least partly. In the following, first the problem caused by the current through the damping impedance is explained, than is elucidated how the measures of the invention overcome this problem.

10 As, during the scan period, the deflection coil may be regarded as a resistor, a relatively small scan voltage suffices to generate the deflection current during the scan period. During the relatively short flyback period, a quick reversal of the deflection current polarity has to be obtained. For such quick current changes, the deflection coil has to be regarded as an inductance, and therefor a large flyback voltage is needed to obtain a short  
15 flyback period. During the scan period, the first and second output amplifiers receive a relative low scan supply voltage to minimize dissipation. During the flyback period, a high flyback supply voltage is connected to the output of the first output amplifier. The flyback supply voltage is connected to the output of the first output amplifier if the current supplied at the input of the first output amplifier increases above a certain level. The flyback voltage  
20 will be disconnected as soon as the current supplied to the input of the first output amplifier decreases below the certain level. It is of course possible to use another information to connect and disconnect the flyback supply voltage, as an example a comparison of the input waveform and the voltage across the series resistor may be used. It is also possible to disconnect the flyback supply voltage at the moment that the output voltage of the first output  
25 amplifier rises above the scan supply voltage.

A damping resistor is arranged in parallel with the deflection coil for smoothening switching points of the currents and voltages which occur in the raster scan circuit, as well to prevent ringing. In an embodiment of the invention it is recognized that the current through the damping resistor depends on the voltage across the deflection coil, and  
30 thus this current has a small value during the scan period and a large value during the flyback period. Due to the large current through the damping resistor during the flyback period, the certain level of the input current of the first output amplifier is reached too early. Consequently, the deflection current has not reached the starting value as is needed at the start of the scan. Depending on the application, this causes compressed lines, bright lines or

flyback lines to become visible. A longer vertical blanking can solve the problem.

The known frame deflection output circuit has an internal compensation for the effect of the current through the damping resistor by adapting a bias current through a differential input stage which measures the voltage across the series resistor. The bias current is enlarged with a fixed amount during the flyback period. As the flyback voltage will be disconnected as soon as the current supplied to the input of the first output amplifier decreases below the certain level, the higher input current causes the period in which the flyback voltage is connected to become longer. The known frame deflection circuit has the drawback that the compensation is optimal only for one combination of the impedance of the deflection coil, the value of the damping resistor, the value of the flyback voltage, and the value of the scan voltage. Further, due to tolerances in the integrated circuit design, the fixed amount with which the bias current is adapted also shows tolerances. The foregoing has the drawback that a longer flyback period or a higher flyback supply voltage has to be chosen. However, a longer flyback period makes the deflection circuit unsuitable for applications requiring a short flyback period. Further, the flyback voltage is limited by the process in which the integrated circuit has been diffused and thus cannot be enlarged above the process limit. Both these facts disable the use of the integrated power circuit in applications in which a satisfactory flyback performance is required at high deflection frequencies and wherein the detrimental effect of the damping impedance is not optimally compensated. This kind of applications which have to cope with high deflection frequencies, such as 100Hz applications, or multimedia applications suitable to display computer display graphics, become more and more important. In these applications, the scan voltage stays in the usual range as the resistance of the deflection coil and not the inductance is relevant during the scan period. However during the short flyback period a high flyback supply voltage is needed as the deflection coil behaves as an inductance. At such a high flyback supply voltage the difference between the flyback supply voltage and the scan supply voltage is much larger than usual. Therefore, in these applications, the influence of the damping impedance on the deterioration of the flyback behaviour is large. At the maximum permissible flyback voltage of the integrated circuit, the shortest possible flyback time is reached with a satisfactory flyback performance by optimally compensating for the influence of the damping impedance. Without an optimal compensation, a distance between scan lines at the start of the scan will be too small (top fold over due to too less compensation), or the distance between scan lines is too large (line spacing due to too much compensation).

In the embodiment of the invention as claimed in claim 2, an optimal



compensation of the influence of the damping impedance is reached by coupling the current generating circuit to the series resistor or the conversion resistor to generate a correction current during at least the last part of the flyback period to compensate for the current through the damping impedance. If the current generating circuit is coupled to the series resistor, the correction current is diverted from the series resistor to prevent the current through the damping impedance to flow through the series resistor.

If the current generating circuit is coupled to the conversion resistor, the correction current is supplied to the conversion resistor to enlarge the current through the conversion resistor. Now, the current through the series resistor is allowed to reach a higher value before the flyback supply voltage will be disconnected, thereby preventing a disconnection of the flyback supply voltage at a too low value of the deflection current. This effect will already be reached if the current generating circuit is active only during the last part of the flyback period. As during the last part of the flyback period the level of the input current to the first output amplifier reaches the certain level at which the flyback supply voltage is disconnected.

Due to the fact that the current generating circuit is coupled to the series resistor or the conversion resistor which are not within the integrated circuit, it is easy to provide a current determining element outside the integrated circuit, so that the amount of correction current generated by the current generating circuit can easily be adapted to fit the demand as determined by the values of the impedances of the deflection coil and the damping impedance thereby enabling an optimal compensation of the current through the damping impedance. So, the deflection circuit according to the invention can be used in applications in which the deflection circuit with the known compensation was not able to reach a satisfactory flyback performance for short flyback times.

The prior art provides a fixed compensation of the influence of the damping impedance by delaying the moment of the disconnecting of the flyback supply voltage. The prior art does not divert a current flowing through the damping impedance from the series resistor during the flyback period to prevent the current through the damping impedance to influence the value of the deflection current. The prior art also does not supply an extra current through the conversion resistor during the flyback period to compensate for the extra current flowing through the series resistor due to the current through the damping impedance.

In an embodiment of the invention as claimed in claim 3, the current flowing through the damping resistor during the flyback period is, at least during the last part

of the flyback period, compensated by generating a correction current which flows through the conversion resistor to enlarge the voltage across the conversion resistor. In this way the current through the series resistor is allowed to reach a higher value before the flyback supply voltage is disconnected.

5 In an embodiment of the invention as claimed in claim 6, the correction current depends on the value of the flyback supply voltage as occurring across the deflection coil. During the flyback period, the current through the damping impedance depends on the flyback voltage. This dependency can be compensated for automatically by generating an amount of correction current that also depends on the flyback voltage. This is advantageous  
10 as the value of the flyback voltage may differ dependent on the impedance of the deflection coil or may vary due to tolerances or aging.

In an embodiment of the invention as claimed in claim 7, the current determining resistor is coupled across the series arrangement of the deflection coil and the series resistor via a pnp transistor which is conductive during the flyback period. A DC-  
15 voltage is applied to the base of the pnp transistor which is selected such that during the scan period this DC-voltage is higher than the scan voltage on the emitter of the pnp transistor such that the pnp transistor does not conduct during the scan period. And, the DC-voltage is selected such that during the flyback period the flyback voltage on the emitter of the pnp transistor is higher than the DC-voltage such that the pnp transistor conducts during the  
20 flyback period. This has the advantage that the transistor is switched automatically by the voltage occurring on the deflection coil without the need for a control circuit.

An embodiment of the invention as claimed in claim 8, has the advantage that a cheap zener diode can be used. The zener diode has a zener voltage large enough to obtain a non-conductive zener diode during the scan period and low enough to obtain a  
25 conducting zener diode during the flyback period. A further advantage is that the voltage across and thus the current through the current determining resistor depends on the actual value of the flyback voltage. This enables a better compensation of the current through the damping impedance which also depends on the flyback voltage during the flyback period.

These and other aspects of the invention will be described and elucidated  
30 with reference to the accompanying drawings.

In the drawings:

Fig. 1 shows a frame deflection circuit according to the prior art,

Fig. 2 shows differential input stages for explaining the occurrence of the

offset,

Fig. 3 shows a picture display apparatus with a frame deflection circuit according to the invention,

Fig. 4 shows a detailed circuit diagram of a frame deflection circuit according to the invention,

Fig. 5 shows waveforms for explaining the effect of a damping resistor, and

Fig. 6 shows circuit diagrams of embodiments of current generating circuits 3 according to the invention.

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Figure 1 shows a frame deflection circuit according to the prior art. The frame deflection circuit comprises a frame deflection coil  $L_f$  arranged in series with a measurement resistor  $R_m$ . The frame deflection circuit further comprises an integrated power circuit which contains a first output amplifier 1, a second output amplifier 2, a first voltage to current converter 8 and a second voltage to current converter 4. The series arrangement of the deflection coil  $L_f$  and the measurement resistor  $R_m$  is connected between an output of the first output amplifier 1 and an output of the second output amplifier 2 to be driven in a bridge configuration for generating a deflection current  $I_f$  through the deflection coil  $L_f$ . A voltage which corresponds to the deflection current  $I_f$  is generated across the measurement resistor  $R_m$ . The voltage across the measurement resistor  $R_m$  is sensed with the first voltage to current converter 8 which has a first and a second current output. To provide a feedback, the first current output is connected to an input of a first output amplifier 1, and the second current output is connected to an input of the second output amplifier 2. An input waveform is generated by an input current  $I_i$  flowing through an input resistor  $R_i$  which is arranged between two inputs of the second voltage to current converter 4. The second voltage to current converter 4 has a first and a second current output. The first current output is connected to the input of the first output amplifier 1, and the second current output is connected to the input of the second output amplifier 2. The first and the second voltage to current converters 8, 4 are identical. The current outputs of the first and the second voltage to current converters 8, 4 which are interconnected supply output currents which have opposite polarities. In this way, the output voltages of the first and second output amplifiers 1, 2 will be controlled such that the voltage across the measurement resistor  $R_m$  is substantially equal to the voltage across the input resistor  $R_i$ . In practical applications the value of the measurement resistor  $R_m$  is in the order of 0.5 Ohms. The deflection current  $I_d$

causes a peak-peak voltage across the measurement resistor  $R_m$  in the order of one volt. The same holds then for the peak-peak voltage of the input waveform. The first and second voltage to current converters 8, 4 comprise bipolar differential input stages T1, T2 (see Fig. 2) with emitter resistors  $R_{e1}$ ,  $R_{e2}$  to handle the high voltage swing. An offset voltage occurs due to mismatch of the emitter resistors  $R_{e1}$ ,  $R_{e2}$ . This offset voltage gives rise to a DC-shift of the deflected picture. A further lowering of the value of the measurement resistor  $R_m$  is not practical as the influence of parasitic effects, such as a resistance and an inductance of tracks on a printed board, becomes too large.

Fig. 2 shows differential input stages for explaining the occurrence of the offset. Figure 2A shows a differential input stage which comprises bipolar transistors of the npn type. A first bipolar transistor T1 has an emitter connected to a first terminal of a current source  $I_s$  via a first emitter resistor  $R_{e1}$ . A second bipolar transistor T2 has an emitter connected to the first terminal of the current source  $I_s$  via a second emitter resistor  $R_{e2}$ . A second terminal of the current source  $I_s$  is connected to a suitable potential which in this case is ground potential. A collector of the first and second bipolar transistor draw a current which depends on an input voltage  $V_i$  supplied by an input voltage source  $V_i$  connected between a basis of the first bipolar transistor and a basis of the second bipolar transistor.

The collector current of a bipolar transistor is expressed as:

$$I_c = I_{cs} \cdot e^{\frac{e \cdot V_{be}}{kT}}$$

The input voltage  $V_i$  between the basis of the bipolar transistor can be

written as:

$$V_{in} = V_{be1} + V_{R_{e1}} - V_{R_{e2}} - V_{be2}$$

$$V_{in} = \frac{kT}{e} \ln \frac{I_{c1}}{I_{cs1}} + I_{c1} \cdot R_{e1} - I_{c2} \cdot R_{e2} - \frac{kT}{e} \ln \frac{I_{c2}}{I_{cs2}}$$

The offset voltage is the input voltage occurring when both collector currents are equal:

$$V_{offset} = \frac{kT}{e} \ln \frac{I_{c2}}{I_{c1}} + \frac{1}{2} I_s \Delta R_e$$

5

So, the offset voltage comprises a fixed term and a term depending on the product of the current flowing in the current source  $I_s$  and the difference of values of the emitter resistors  $R_{e1}$ ,  $R_{e2}$ . The offset voltage increases if the current flowing in the current source  $I_s$  or the values of the emitter resistors  $R_{e1}$ ,  $R_{e2}$  has to be increased to cope with a large input voltage swing.

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Figure 2B shows a differential input stage which comprises field effect transistors (further denoted with FET). A source of a first FET M1 and a source of a second FET M2 are connected to a first terminal of a current source  $I_s$ . A second terminal of the current source  $I_s$  is connected to a suitable potential. A drain of the first and second FET draw a current which depends on an input voltage  $V_i$  supplied by an input voltage source  $V_i$  connected between a gate of the first FET and a gate of the second FET.

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The drain current of a FET can be expressed as:

$$I_d = \frac{\beta}{2} \cdot (V_{gs} - V_T)^2$$

20

wherein:

$$\beta = \mu \cdot C_{ox} \cdot \frac{W}{L}$$

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$W$  = width of channel

$L$  = length of channel

$C_{ox}$  = capacity of oxide between gate and channel

$\mu$  = mobility of the charge carriers.

The input voltage  $V_i$  between the gates of the FET's can be written as:

$$V_{in} = V_{gs1} - V_{gs2}$$

5

$$V_{in} = \sqrt{\frac{2I_{d1}}{\beta_1} + V_{T1}} - \sqrt{\frac{2I_{d2}}{\beta_2} + V_{T2}}$$

The offset voltage is the input voltage occurring when both drain currents are equal:

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$$V_{offset} = \sqrt{I_s} \cdot \left[ \frac{1}{\sqrt{\beta + \frac{1}{2}\Delta\beta}} - \frac{1}{\sqrt{\beta - \frac{1}{2}\Delta\beta}} \right] + \Delta V_T$$

So, the offset voltage comprises a fixed term and a term depending on the current flowing in the current source  $I_s$ . The offset voltage increases if the current flowing in the current source  $I_s$  has to be enlarged to cope with a large input voltage swing.

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Fig. 3 shows a picture display apparatus with a frame deflection circuit according to the invention. The picture display apparatus further comprises a synchronisation circuit 4, a frame deflection coil  $L_f$ , and a cathode ray tube CRT. The synchronisation circuit 4 receives a frame synchronisation signal  $S_f$  of a video signal, and generates a reference waveform which is supplied to an input of the frame deflection circuit as an input current  $I_i$ . The deflection coil is magnetically coupled to the cathode ray tube CRT to generate a frame deflection of electron beams in the cathode ray tube CRT. The frame deflection may be a deflection in the vertical direction if a picture is composed by subsequently scanning horizontal lines in the vertical direction, as is common practice. The frame deflection may be a deflection in horizontal direction if a picture is composed by subsequently scanning vertical lines in the horizontal direction, as is the case with the so

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called transposed scanning. Although the invention is particularly useful in frame deflection circuits, it is also possible to drive a line deflection coil with the deflection circuit according to the invention. The frame deflection circuit comprises an integrated power circuit which contains a first output amplifier 1, a second output amplifier 2, and a differential amplifier 5, a series resistor  $R_s$ , and a conversion resistor  $R_c$ . The series resistor  $R_s$  is arranged in series with the deflection coil  $L_f$ . The series arrangement of the deflection coil  $L_f$  and the series resistor  $R_s$  is connected between an output of the first output amplifier 1 and an output of the second output amplifier 2 to be driven in a bridge configuration for generating a deflection current  $I_f$  through the deflection coil  $L_f$ . Across the series resistor  $R_s$ , a voltage is generated which corresponds to the deflection current  $I_f$ . The differential amplifier 5 has a first input connected to a connection point of the deflection coil  $L_f$  and the series resistor  $R_s$ . A second input of the differential amplifier 5 is connected via the conversion resistor  $R_c$  to an end of the series resistor  $R_s$  which is not connected to the deflection coil  $L_f$ . An input current source 6 is connected to the second input of the differential amplifier 5 to supply an input current  $I_i$  which flows through the conversion resistor  $R_c$ . Thus, the differential amplifier 5 receives between its inputs the voltage across a series arrangement of the conversion resistor  $R_c$  and the series resistor  $R_s$ . The polarity of the input current  $I_i$  is selected to obtain a voltage across the conversion resistor  $R_c$  which has an opposite polarity with respect to the voltage across the series resistor  $R_s$ . The differential amplifier 5 has two outputs connected to respective inputs of the first and the second output amplifiers 1, 2 to drive the two output amplifiers 1, 2 in a feedback loop such that the voltage across the series arrangement of the conversion resistor  $R_c$  and the series resistor  $R_s$  becomes equal to zero. In this way, the voltage swing between the inputs of the differential amplifier 5 is very low. In case the differential amplifier contains a bipolar differential input stage, the emitter resistors  $R_{e1}$ ,  $R_{e2}$  (see Fig. 2A) can be modified to a lower value or can even be omitted and thus the offset caused becomes very low. In case the differential amplifier contains a FET input stage, the current flowing through the current source  $I_s$  (see Fig. 2B) can be decreased thereby obtaining a lower offset. It is assumed that the first output amplifier 1 supplies the high flyback voltage during the flyback period. The differential amplifier 5 only needs to withstand the scan supply voltage.

The conversion resistor  $R_c$  may alternatively be arranged between the first input of the differential amplifier 5 and the connection point of the deflection coil  $L_f$  and the series resistor  $R_s$ . In this case, the value of the conversion resistor  $R_c$  should be large enough to prevent the input current which flows through it to disturb the voltage across the

series resistor  $R_s$  too much. The polarity of the input current has to be chosen to withdraw current from the first input of the differential amplifier 5 to obtain a voltage across the conversion resistor  $R_c$  in opposite polarity to the voltage across the series resistor  $R_s$ .

With regard to the above described two embodiments, it is also possible to exchange the position of on the one hand the deflection coil  $L_f$  and on the other hand the series resistor  $R_s$  with the thereto coupled conversion resistor  $R_c$  and differential amplifier 5. The differential amplifier 5 should then be able to withstand the flyback voltage.

If one end of the conversion resistor  $R_c$  is connected to an output of the first or the second output amplifier 1, 2, the buffer can be replaced by a differential to single converter. This converter generates a single output current or voltage connected to the other end of the conversion resistor  $R_c$ . Such a single output converter has a simpler construction than a buffer thereby decreasing the offset. Although the above described frame deflection circuit is based on a differential amplifier 5 with current outputs and a first and second output amplifier 1, 2 with current inputs, numerous alternatives are possible. As an example, the differential amplifier 5 may supply a voltage to the input of the first output amplifier 1. An inverter stage inverts this voltage to supply the inverted voltage to the second output stage 2.

Fig. 4 shows a more detailed frame deflection circuit according to the invention. This frame deflection circuit comprises a first and a second output amplifier 1, 2 arranged in a bridge configuration. Each of the output amplifiers 1, 2 receives a scan supply voltage  $V_p$ . The first output amplifier 1 has an output which supplies a voltage  $V_a$ , the second output amplifier 2 has an output which supplies a voltage  $V_b$ . A series arrangement of a deflection coil  $L_f$  and a series resistor  $R_s$  is connected between the output of the first output amplifier 1 and the output of the second output amplifier 2. The damping resistor  $R_d$  is arranged in parallel with the deflection coil  $L_f$ . A flyback supply voltage  $V_{fb}$  is connected via a semiconductor switch  $T_1$  which is shown as a field effect transistor (further denoted as FET) to the output of the first output amplifier 1. The FET  $T_1$  connects the flyback supply voltage  $V_{fb}$  to the deflection coil  $L_f$  during the flyback period  $T_f$ . The differential amplifier 5 comprises a first FET  $T_2$ , a second FET  $T_3$  and a current source  $I_s$ . The source of the first FET  $T_2$  is connected to the source of the second FET  $T_3$  and to one end of the current source  $I_s$ . The other end of the current source  $I_s$  is connected to the scan supply voltage  $V_p$ . A gate of the first FET  $T_2$  is connected to a connection point of the deflection coil  $L_f$  and the series resistor  $R_s$ . This connection point is further referred to as the second connection



point P2. A gate of the second FET T3 is connected to the output of the second output amplifier 2 via a conversion resistor  $R_c$ , and receives the input current  $I_i$ . The gates of the first and second FET's T2, T3 constitute a first and second input of the differential amplifier 5. The connection point of the gate of the second FET T3 and the conversion resistor  $R_c$  is further referred to as the connection point P1. A drain of the first FET T2 is connected to an input of the first output amplifier 1. A drain of the second FET T3 is connected to an input of the second output amplifier 2. The drains of the first and second FET's T2, T3 constitute outputs of the differential amplifier 5. The current generating circuit 3 is connected to the first or second connection point P1, P2.

This frame deflection circuit operates as follows. The input current  $I_i$  causes a reference voltage  $V_r$  across the conversion resistor  $R_c$ . The current  $I_s$  through the series resistor  $R_s$  causes a voltage  $V_s$  across the series resistor  $R_s$ . The differential amplifier 5 receives the sum of the voltage  $V_s$  and the reference voltage  $V_r$  between its inputs, and supplies currents at its outputs to drive the first and the second output amplifiers 1, 2 such that this sum is kept zero. In this way the output amplifiers 1, 2 are controlled to supply the output voltages  $V_a$ ,  $V_b$  to obtain a voltage  $V_s$  across the series resistor  $R_s$  which has an opposite polarity with respect to the reference voltage  $V_r$ . The influence of the damping resistor  $R_d$  and the corrective action of the current generating circuit 3 are elucidated in the description of Figure 5.

Figure 5A shows waveforms of the current  $I_s$  through the series resistor  $R_s$ , the deflection current  $I_f$ , and the current  $I_d$  through the damping resistor  $R_d$ , respectively, all as a function of time. The deflection current  $I_f$  is represented by a dashed line. Figure 5B shows the voltage  $V_a$ - $V_b$  occurring across the series arrangement of the deflection coil  $L_f$  and the series resistor  $R_s$ . Especially during the flyback period this is a simplified waveform. Moment  $t_1$  denotes the start of a scan period  $T_s$ . Moment  $t_2$  denotes the middle of the scan period. Moment  $t_3$  denotes the end of the scan period  $T_s$  and the start of the flyback period  $T_f$ . Moment  $t_4$  denotes the end of the flyback period  $T_f$  and the start of a subsequent scan period  $T_s$ . For clarity the duration of the flyback period  $T_f$  has been exaggerated.

During the scan period  $T_s$ , in a first approximation, the deflection coil  $L_f$  behaves as a resistor. So, the voltage across the deflection coil  $L_f$  should be substantially sawtooth shaped to obtain a substantial sawtooth current through the deflection coil  $L_f$ . At the start  $t_1$  of a scan period  $T_s$ , the output voltage  $V_a$  of the first output amplifier 1 is

approximately equal to the scan supply voltage  $V_p$ , the output voltage  $V_b$  of the second output amplifier 2 is approximately equal to ground potential, and thus approximately a scan supply voltage  $V_p$  occurs across the deflection coil  $L_f$ . The scan voltage  $V_p$  is selected to be high enough to generate a desired maximum value of the deflection current  $I_f$ , and as low as possible to minimize the dissipation in the first output amplifier 1. The value of this scan supply voltage  $V_p$  also determines the current  $I_d$  through the damping impedance  $R_d$  during the scan period. The current  $I_s$  through the series resistor  $R_s$  is composed out of the deflection current  $I_f$  through the deflection coil  $L_f$  and the current  $I_d$  through the damping resistor  $R_d$ . The differential amplifier 5 receives the addition of the voltage  $V_s$  across the series resistor  $R_s$  and the voltage  $V_r$  across the conversion resistor  $R_c$ . The differential amplifier drives the first and second output amplifiers 1, 2 to supply a value of the output voltages  $V_a$  and  $V_b$  such that the voltage  $V_s$  occurring across the series resistor  $R_s$  becomes equal in value but opposite in polarity to the voltage  $V_r$  across the conversion resistor  $R_c$ . Due to the fact that the voltage  $V_r$  across the series resistor  $R_s$  is also determined by the current  $I_d$  through the damping resistor  $R_d$ , the actual deflection current  $I_d$  has a somewhat lower amplitude compared with the situation without a damping resistor  $R_d$ .

At the end  $t_4$  of the flyback period  $T_f$  a flyback supply voltage  $V_{flb}$  occurs across the deflection coil  $L_f$ . During the flyback period  $T_f$ , in a first approximation, the deflection coil  $L_f$  acts as an inductance. This flyback supply voltage  $V_{flb}$  has a larger value than the scan supply voltage  $V_p$  to be able to change the polarity of the deflection current  $I_f$  within the short flyback period  $T_f$ . Thus, the current  $I_d$  through the damping resistor  $R_d$  is larger during the flyback period  $T_f$  than during the scan period  $T_s$ . The flyback supply voltage  $V_{flb}$  will be disconnected from the deflection coil  $L_f$  at the moment an input current of the first output amplifier 1 decreases below a certain value. Or, alternatively, the voltage  $V_r$  across the series resistor  $R_s$  reaches the flyback voltage level of the reference waveform  $Ref$ . Due to the high extra current through the series resistor  $R_s$  caused by the high voltage across the damping resistor  $R_d$ , the disconnection of the flyback supply voltage  $V_{flb}$  is activated at a relatively low value of the deflection current  $I_f$ . So, the value of the deflection current  $I_f$  at the end  $t_4$  of the flyback period  $T_f$  is lower than the amount of deflection current  $I_f$  as desired at the start  $t_1$ ,  $t_4$  of the scan period  $T_s$ . This difference in amounts of the deflection current  $I_f$ , is denoted in Figure 5A as  $g$ . Before starting a next frame scan, the too low amount of deflection current ( $I_f$ ) at the end  $t_4$  of the flyback period  $T_f$  has to increase to the higher amount of the deflection current  $I_f$  as desired at the start  $t_4$  of the scan period  $T_s$ . This transition has to be performed with the low scan supply voltage

$V_p$  (as an example, a practical value is 14 volts) and thus will take substantially more time than is the case if the flyback can be wholly performed with the high flyback supply voltage  $V_{fb}$  (as an example, a practical value is 60 volts).

The frame deflection circuit according to the invention solves this problem by adding a current generating circuit 3 which is coupled to the series resistor  $R_s$  and/or the conversion resistor  $R_c$  to generate a correction current  $I_c$  during at least the last part of the flyback period  $T_f$ . If the current generating circuit 3 is connected to the series resistor  $R_s$ , the correction current  $I_c$  is diverted from the series resistor  $R_s$  to prevent the current  $I_d$  through the damping impedance  $R_d$  to flow through the series resistor  $R_s$ . If the current generating circuit 3 is coupled to the conversion resistor  $R_c$ , the correction current  $I_c$  enlarges the input voltage  $V_i$  across the conversion resistor  $R_c$ . Now, the current through the series resistor  $R_s$  is allowed to reach a higher value before the flyback supply voltage  $V_{fb}$  will be disconnected, thereby preventing a disconnection of the flyback supply voltage  $V_{fb}$  at a too low value of the deflection current  $I_f$ .

Fig. 6 shows circuit diagrams of embodiments of current generating circuits 3 according to the invention.

The embodiments shown in Fig. 6A to 6D generate a current  $I$  to a connection point  $P$ . This point  $P$  may be the first connection point  $P_1$  which denotes the connection point of the current generating means 3 and the conversion resistor  $R_c$  or the second connection point  $P_2$  which denotes the connection point of the current generating means 3 and the series resistor  $R_s$ . In these cases the current  $I$  is the correction current  $I_c$ . The current  $I$  may also be supplied as the reference current  $I_{ref}$  to an input  $P_3$  of the current mirror as shown in Fig. 6E.

In the frame deflection circuit shown in Fig. 4, the current generating circuit 3 supplies a correction current  $I_c$  to the first connection point  $P_1$  to enlarge the voltage  $V_i$  across the conversion resistor  $R_c$ . If the current generating circuit 3 is connected in other ways to the conversion resistor  $R_c$ , the direction of the correction current  $I_c$  again has to be selected such as to enlarge the voltage across the conversion resistor  $R_c$ . If the current generating circuit 3 is connected to the second connection point  $P_2$ , as shown in Fig. 4, the correction current  $I_c$  should be withdrawn from the series resistor  $R_s$  to divert the current  $I_d$  flowing through the damping impedance  $R_d$  from the series resistor  $R_s$ . If the position of the deflection coil  $L_f$  and the series resistor  $R_s$  are interchanged, the correction circuit 3 which is still connected to the connection point of the deflection coil  $L_f$  and the

series resistor  $R_s$  has to supply the correction current  $I_c$  to the series resistor  $R_s$  such that the current  $I_d$  through the damping impedance  $R_d$  will not flow through the series resistor  $R_s$ .

Fig. 6A shows a series arrangement of a current determining resistor  $R_1$  and a semiconductor switch  $S$ . The series arrangement receives a voltage  $V_d$  and supplies a current  $I$  to the connection point  $P$  during a conduction period of the semiconductor switch  $S$ . A control input of the semiconductor switch  $S$  receives a control signal  $C_2$  which causes the semiconductor switch  $S$  to conduct at least during a last part of the flyback period  $T_f$ . The current  $I$  depends on the values of the voltage  $V_d$  and the current determining resistor  $R_1$ . the voltage  $V_d$  has to be selected to supply the current  $I$  in the desired direction.

Fig. 6B differs from Fig. 6A in that the voltage  $V_d$  is selected to be a deflection voltage  $V_a$ ,  $V_b$  at the end of the deflection coil  $L_f$  not connected to the series resistor  $R_s$ . In this way the current  $I$  depends on the flyback voltage  $V_{fb}$ .

In Fig. 6C, the semiconductor switch  $S$  is a pnp transistor  $T_6$  which has an emitter connected to the voltage  $V_a$  at the output of the first output amplifier 1 via the current determining resistor  $R_1$ . The base of the pnp transistor  $T_6$  is connected to a DC-voltage selected such that the pnp transistor  $T_6$  conducts during the flyback period  $T_f$  during which the deflection voltage  $V_a$  is approximately equal to the high flyback supply voltage  $V_{fb}$ . The collector of the pnp transistor  $T_6$  supplies the current  $I$ .

Fig. 6D differs from Fig. 6C in that the pnp transistor  $T_6$  is replaced by a zener diode  $D_1$ . An anode of the zener diode  $D_1$  is directed towards the connection point  $P$  if the supply voltage is the output voltage  $V_a$  of the first output amplifier 1. It is clear that in the situation that a current  $I$  has to be withdrawn, the output voltage  $V_a$  of the first output amplifier 1 has to be replaced by the output voltage  $V_b$  of the second output amplifier 2 and that the direction of the zener diode  $D_1$  has to be altered.

Fig. 6E shows a current generating circuit 3 which comprises a current mirror with a first transistor  $T_4$  and a second transistor  $T_5$  both of the npn type, and a third transistor  $T_6$  of the pnp type. A base and a collector of the first transistor  $T_4$  are interconnected. The base of the first transistor  $T_4$  is connected to a base of the second transistor  $T_5$ . The emitters of the first and the second transistor  $T_4$ ,  $T_5$  are connected to the same voltage, which in Figure 6E is ground potential. A collector of the second transistor  $T_5$  is connected to the first or second connection point  $P_1$ ,  $P_2$  to supply the correction current  $I_c$ . An emitter of the third transistor  $T_6$  receives a reference current  $I_{ref}$  at the connection point  $P_3$ . The third transistor  $T_6$  has a base connected to the scan supply voltage  $V_p$  or any other suitable fixed voltage, and a collector connected to the collector of the first transistor

T4. The current through the first transistor T4 is determined by the reference current  $I_{ref}$ . This reference current  $I_{ref}$  is mirrored by the first and second transistor T4, T5 to obtain the correction current  $I_c$ . It is also possible to connect the emitters of the first and second transistor T4, T5 to a suitable voltage which is lower than the scan supply voltage  $V_p$  and the voltage on the first or second connection point P1, P2, as may be the case with the output voltage  $V_b$  of the second output amplifier 2. The reference current  $I_{ref}$  can be generated in any of the ways shown in Fig. 6A to 6D.

Fig. 6F shows a current generating circuit 3 which comprises a series arrangement of a resistor R1 and a semiconductor switch S, whereby the series arrangement is arranged in parallel with the series resistor  $R_s$ . A control input of the semiconductor switch S receives a control signal C2 which causes the semiconductor switch S to conduct at least during a last part of the flyback period  $T_f$ .

While the invention has been described in connection with preferred embodiments, it will be understood that modifications thereof within the principles outlined above will be evident to those skilled in the art and thus the invention is not limited to the preferred embodiments but is intended to encompass such modifications. Any reference signs in the following claims shall not be construed as limiting the claims.

## Claims.

1. A deflection circuit for generating an electron beam deflection current ( $I_f$ ) in a deflection coil ( $L_f$ ), the deflection circuit comprising:  
a first and a second output amplifier (1,2),  
a series resistor ( $R_s$ ) arranged in series with the deflection coil ( $L_f$ ), the  
5 series arrangement of the deflection coil ( $L_f$ ) and the series resistor ( $R_s$ ) being coupled between an output of the first output amplifier (1) and an output of the second output amplifier (2),  
a differential amplifier (5) having a first input coupled to a first end of the series resistor ( $R_s$ ), and having outputs coupled to corresponding inputs of the first and the  
10 second output amplifier (1,2), respectively, for driving the first and second output amplifiers (1,2) in a bridge configuration,  
characterized in that the deflection circuit further comprises a conversion resistor ( $R_c$ ) having:  
a first end coupled to a second input of the differential amplifier (5), the  
15 first end receiving an input current ( $I_i$ ) having an input waveform, and  
a second end coupled to a second end of the series resistor ( $R_s$ ).
2. A deflection circuit as claimed in claim 1, wherein the deflection circuit further comprises:  
20 a damping impedance ( $R_d$ ) arranged in parallel with the deflection coil ( $L_f$ ), and  
current generating means (3) coupled to the series resistor ( $R_s$ ) to divert a correction current ( $I_c$ ) from the series resistor ( $R_s$ ) during at least a last part of a flyback period ( $T_f$ ) of the deflection current ( $I_f$ ).
- 25 3. A deflection circuit as claimed in claim 1, wherein the deflection circuit further comprises:  
a damping impedance ( $R_d$ ) arranged in parallel with the deflection coil ( $L_f$ ), and

current generating means (3) coupled to the second input of the differential amplifier (5) to supply a correction current ( $I_c$ ) for enlarging the current ( $I_i$ ) through the conversion resistor ( $R_c$ ) during at least a last part of a flyback period ( $T_f$ ) of the deflection current ( $I_f$ ).

5

4. A deflection circuit as claimed in claim 2 or 3, wherein the current generating means (3) comprise a current mirror ( $T_4, T_5$ ) having an input for receiving a reference current ( $I_r$ ) and an output supplying the correction current ( $I_c$ ) in relation to the reference current ( $I_r$ ).

10

5. A deflection circuit as claimed in claim 2, 3 or 4, wherein the current generating means (3) further comprise:

a series arrangement of a current determining impedance ( $R_1$ ) and a semiconductor switch ( $S$ ) being coupled between a voltage source ( $V_d$ ) and the conversion resistor ( $R_c$ ), or the series resistor ( $R_s$ ) or the input of the current mirror ( $T_4, T_5$ ), and

15

a control circuit (7) receiving information related to the flyback period and being coupled to the semiconductor switch ( $S$ ) to cause the semiconductor switch ( $S$ ) to be conductive during at least the last part of the flyback period ( $T_f$ ).

20

6. A deflection circuit as claimed in claim 5, wherein the deflection circuit further comprises means ( $T_1$ ) for connecting a flyback supply voltage ( $V_{fb}$ ) to the output of the first output amplifier (1) during the flyback period ( $T_f$ ), and wherein the voltage source ( $V_d$ ) is constituted by a deflection voltage ( $V_a, V_b$ ) at an end of the deflection coil ( $L_f$ ) not being coupled to the series resistor ( $R_s$ ).

25

7. A deflection circuit as claimed in claim 2, 3 or 4, wherein the deflection circuit further comprises means ( $T_1$ ) for connecting a flyback supply voltage ( $V_{fb}$ ) to the output of the first output amplifier (1) during the flyback period ( $T_f$ ), and wherein the current generating means (3) comprise a transistor ( $T_6$ ) of the pnp type having a control

30

electrode, and a main current path being arranged in series with a current determining impedance ( $R_1$ ), an emitter of the transistor ( $T_6$ ) being coupled to an end of the deflection coil ( $L_f$ ) not being coupled to the series resistor ( $R_s$ ) via the current determining impedance ( $R_1$ ), an collector of the transistor ( $T_6$ ) being coupled to the conversion resistor ( $R_c$ ) or the series resistor ( $R_s$ ) or the input of the current mirror ( $T_4, T_5$ ), whereby the control electrode

receives a DC-voltage ( $V_{dc}$ ) for obtaining the transistor (T6) conductive during the flyback period ( $T_f$ ) and non conductive during the scan period ( $T_s$ ).

8. A deflection circuit as claimed in claim 2, 3 or 4, wherein the deflection  
5 circuit further comprises means (T1) for connecting a flyback supply voltage ( $V_{flb}$ ) to the output of the first output amplifier (1) during the flyback period ( $T_f$ ), and wherein the current generating means (3) comprise a zener diode (D1) being arranged in series with a current determining impedance (R1), the series arrangement being coupled between the end of the deflection coil ( $L_f$ ) not being coupled to the series resistor ( $R_s$ ), and the conversion  
10 resistor ( $R_c$ ) or the series resistor ( $R_s$ ) or the input of the current mirror (T4, T5), and whereby the zener diode (D1) is directed to be conductive during the flyback period ( $T_f$ ) and non conductive during the scan period ( $T_s$ ).

9. A deflection circuit as claimed in claim 2, wherein the current generating  
15 means (3) comprise:

a series arrangement of a semiconductor switch (S) and a current determining impedance (R1) being coupled in parallel to the series resistor ( $R_s$ ) to divert the correction current ( $I_c$ ) from the series resistor ( $R_s$ ), and

a control circuit (7) receiving information related to the flyback period  
20 ( $T_f$ ) and being coupled to the semiconductor switch (S) to cause the semiconductor switch to be conductive during at least the last part of the flyback period ( $T_f$ ).

10. A picture display apparatus comprising:

a cathode ray tube (CRT) with a frame deflection coil ( $L_f$ ),

25 a frame deflection circuit generating a deflection current ( $I_f$ ) through the frame deflection coil ( $L_f$ ) for deflecting an electron beam in the cathode ray tube (CRT), the frame deflection circuit comprising:

a first and a second output amplifier (1,2),

a series resistor ( $R_s$ ) being arranged in series with the deflection coil ( $L_f$ ),  
30 the series arrangement of the deflection coil ( $L_f$ ) and the series resistor ( $R_s$ ) being coupled between an output of the first output amplifier (1) and an output of the second output amplifier (2),

a differential amplifier (5) having a first input being coupled to a first end of the series resistor ( $R_s$ ), and having outputs being coupled to corresponding inputs of the



first and the second output amplifier (1,2), respectively, for driving the first and second output amplifiers (1,2) in a bridge configuration, characterized in that the frame deflection circuit further comprises a conversion resistor ( $R_c$ ) having:

- 5                   a first end being coupled to a second input of the differential amplifier (5), the first end receiving an input current ( $I_i$ ) having an input waveform, and  
                  a second end being coupled to a second end of the series resistor ( $R_s$ ).

11.               An integrated circuit for use in a deflection circuit as claimed in claim 1,  
10   whereby the integrated circuit comprises the first and the second output amplifier (1,2), and the differential amplifier (5).

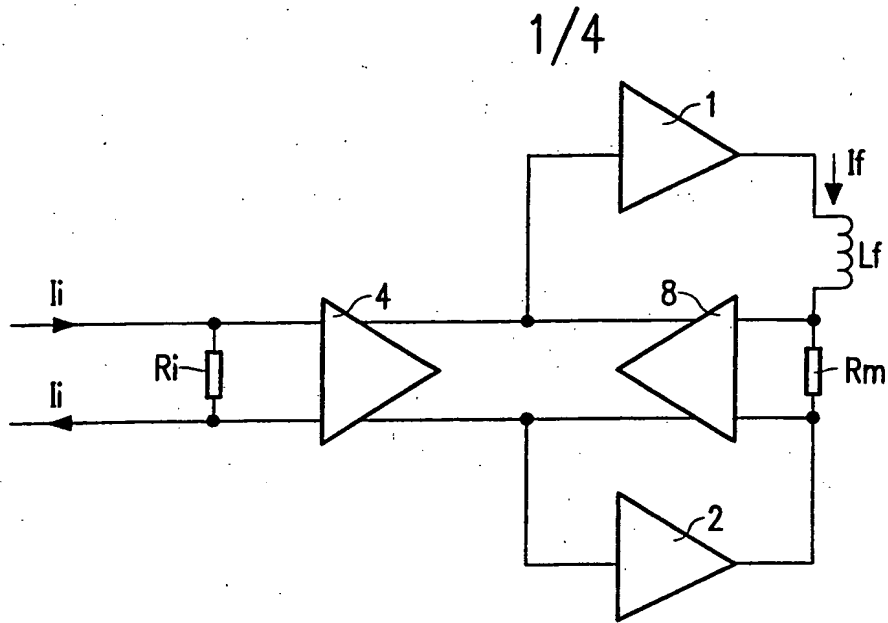


FIG. 1

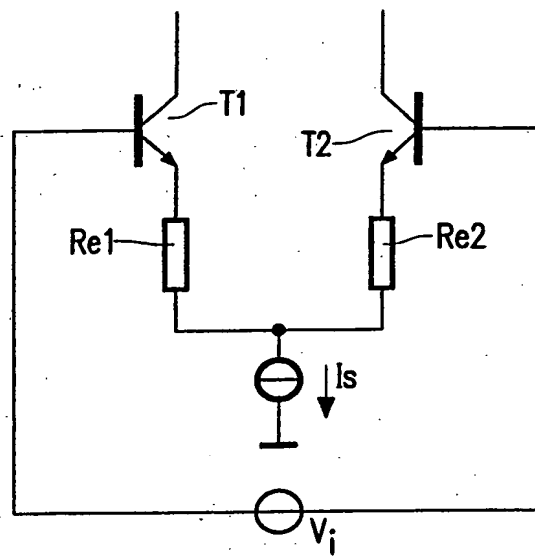


FIG. 2A

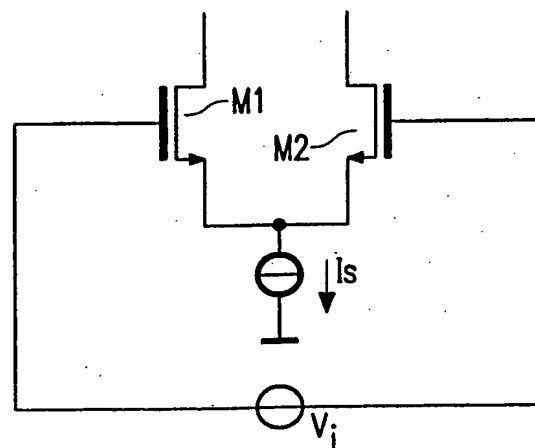


FIG. 2B

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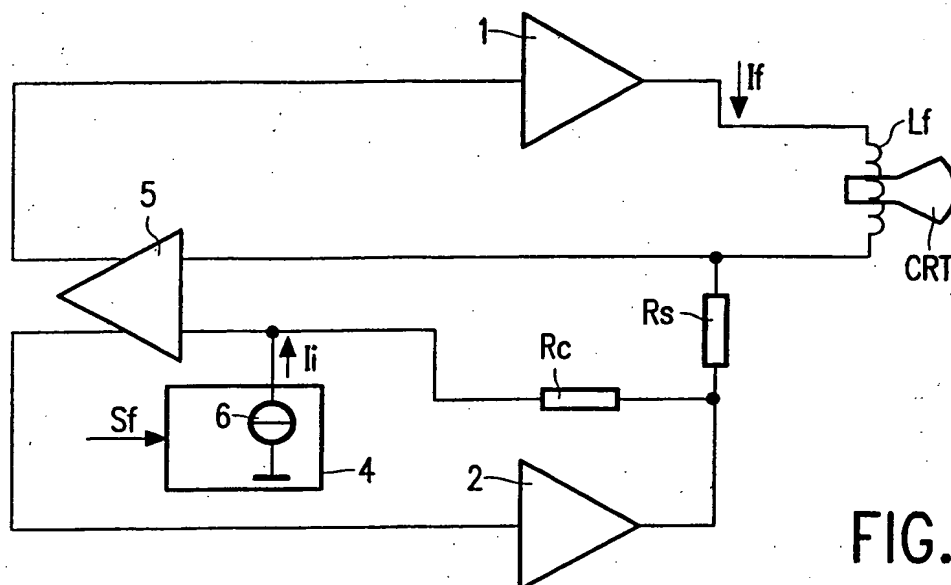


FIG. 3

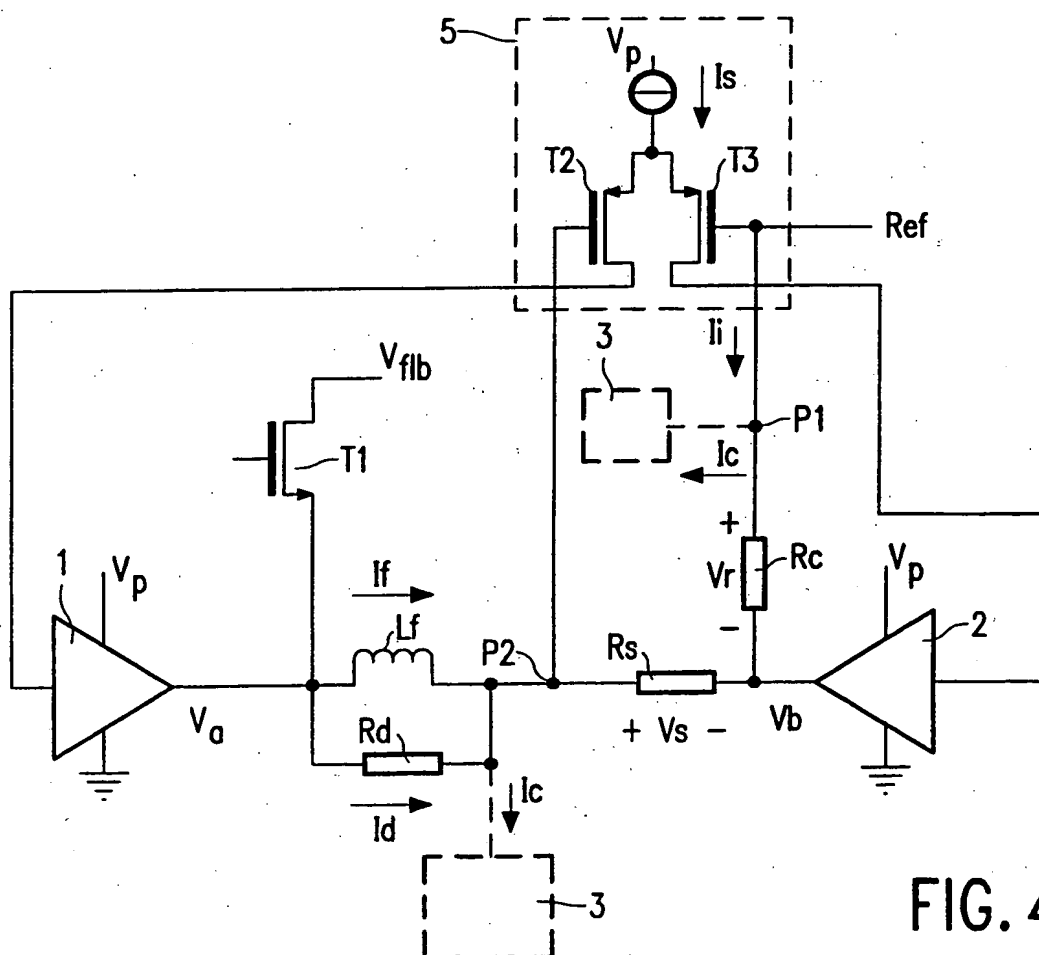


FIG. 4

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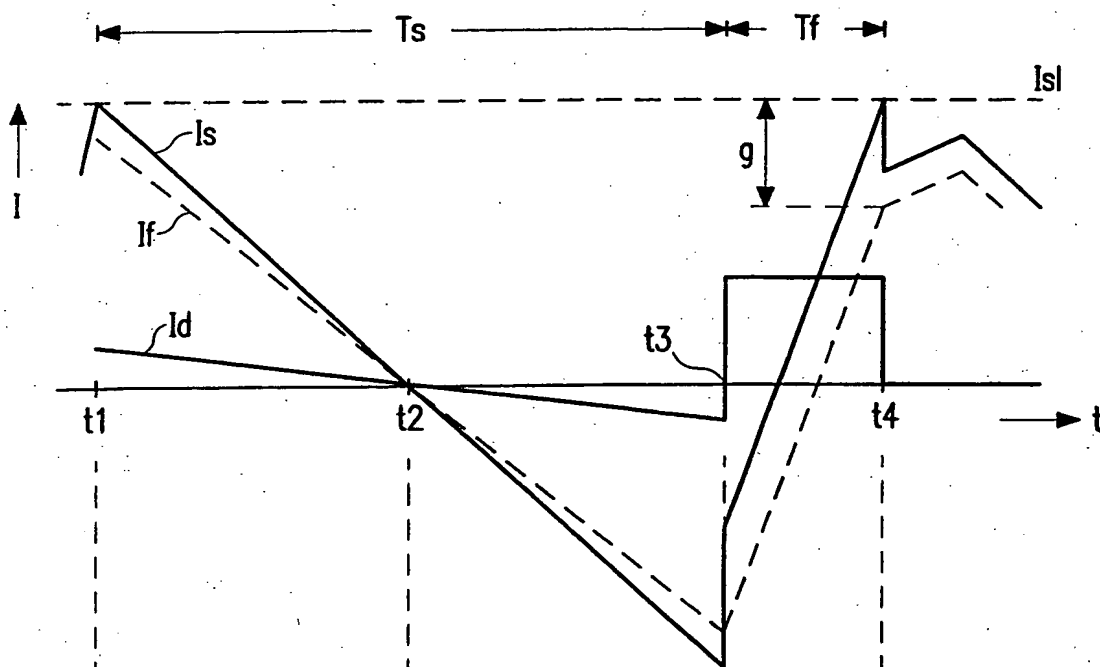


FIG. 5A

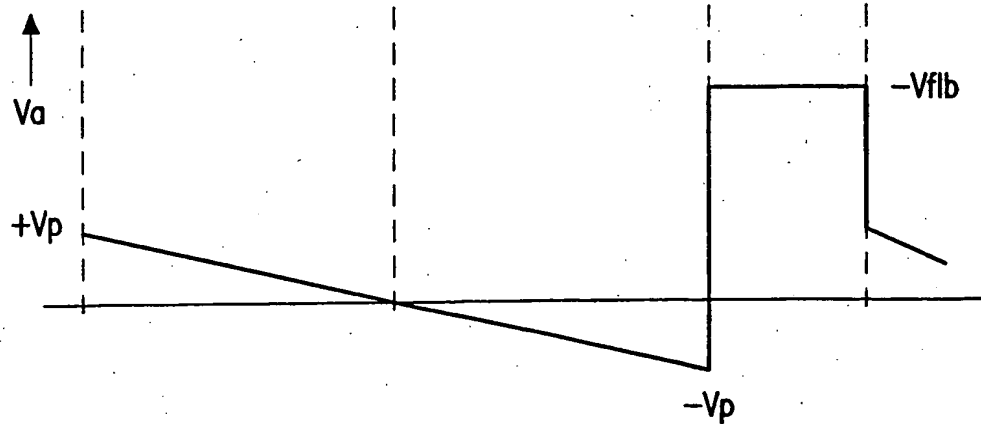


FIG. 5B

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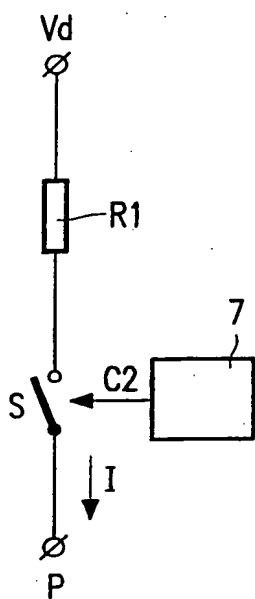


FIG. 6A

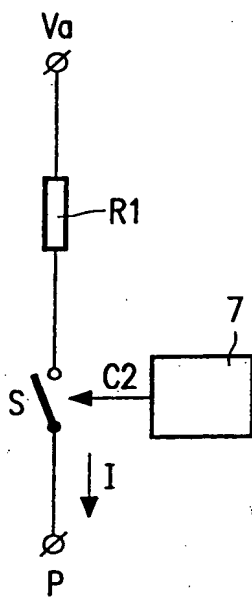


FIG. 6B

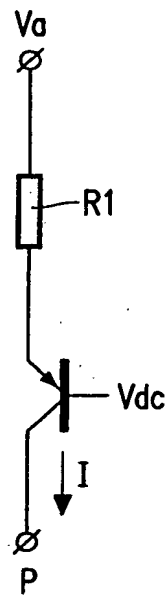


FIG. 6C

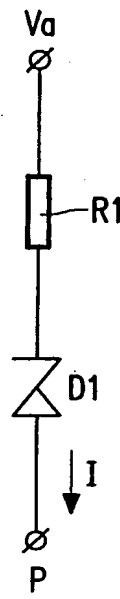


FIG. 6D

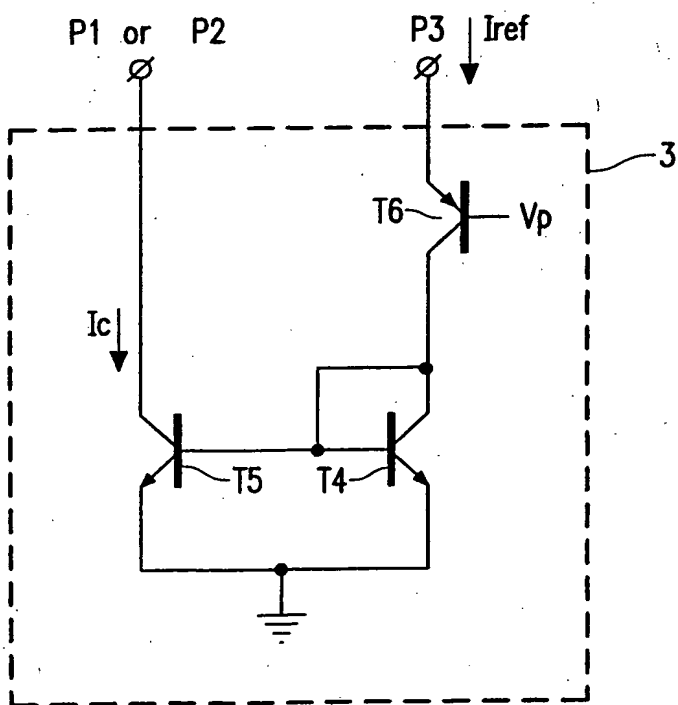


FIG. 6E

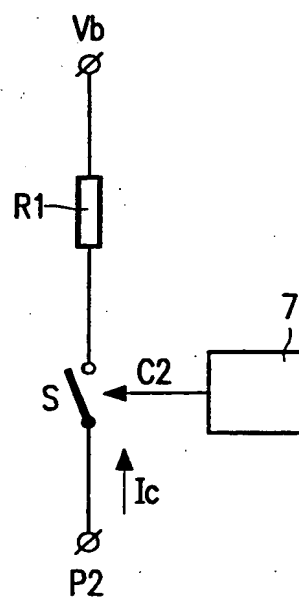


FIG. 6F